

# The Information-Theoretic Value of Unlabeled Data in Semi-Supervised Learning



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### **The Problem**

- ullet Distribution D over a domain X
- Unknown target function f from a known hypothesis class  $H \subseteq \{0,1\}^X$ .
- Learner receives  $S = ((x_1, f(x_1)), (x_2, f(x_2)), \dots, (x_m, f(x_m)))$ .

# Does knowing D help?

# **Sample Complexity**

- Learning algorithm outputs a classifier g = A(S).
- Its error is

$$\operatorname{err}_D(g) = \Pr_{x \in D}[f(x) \neq g(x)]$$

• Sample complexity is the smallest  $m=m(\epsilon,\delta,D)$  such that for any target  $f\in H$ , with probability  $\geq 1-\delta$ 

$$\operatorname{err}_D(g) \leq \epsilon$$

### **Known Results**

ullet Without knowing D the sample complexity is

$$O\left(\frac{\mathrm{VC}(H) + \log(1/\delta)}{\epsilon}\right)$$

Modulo log factors this is achieved by any constistent algorithm, i.e. ERM.

 $\bullet$  With knowledge of D, the sample complexity is at most

$$O\left(\frac{\log N_{D,\epsilon/2} + \log(1/\epsilon)}{\delta}\right)$$

where  $N_{D,\epsilon/2}$  is  $\frac{\epsilon}{2}$ -covering number of H under the metric

$$d(f,g) = \Pr_{x \sim D}[f(x) \neq g(x)].$$

Covering number upper bound

$$N_{D,\epsilon} \le \left(\frac{4e}{\epsilon}\right)^{\frac{VC(H)}{1 - 1/\epsilon}}$$

ullet There exists a distribution D such that **even with knowledge of** D, any algorithm needs at least

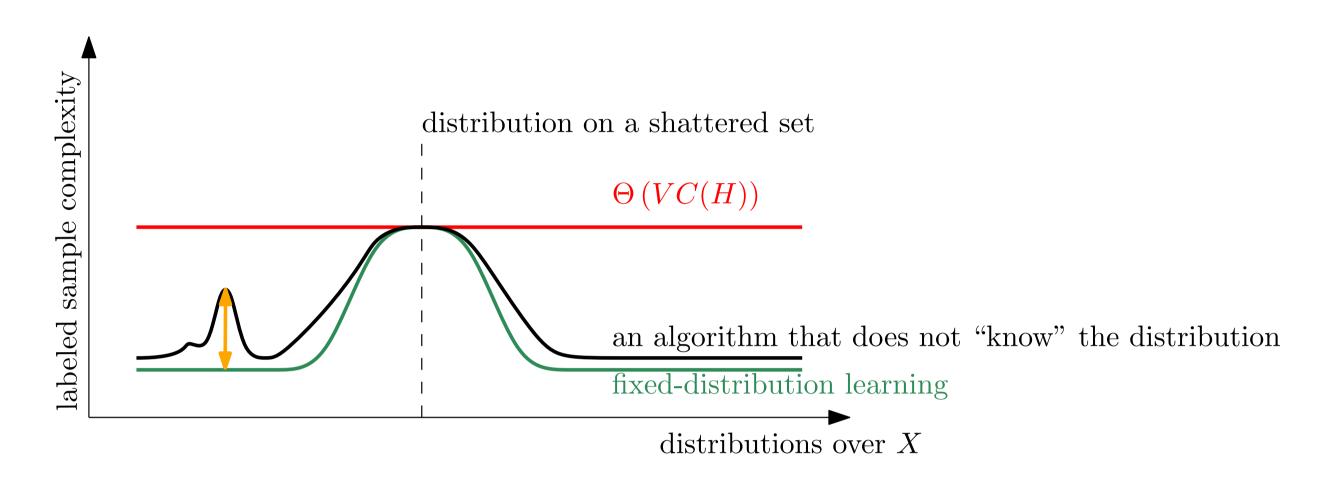
$$\Omega\left(\frac{\mathrm{VC}(H) + \log(1/\delta)}{\epsilon}\right)$$

labeled examples.

• There are distributions D such that any constistent algorithm has sample complexity only  $O(\log(1/\delta)/\epsilon)$ .

# **Summary of Known Results**

Fix  $\epsilon$  and  $\delta$ .



How big is the gap between the black and the green curve?

# **Projections**

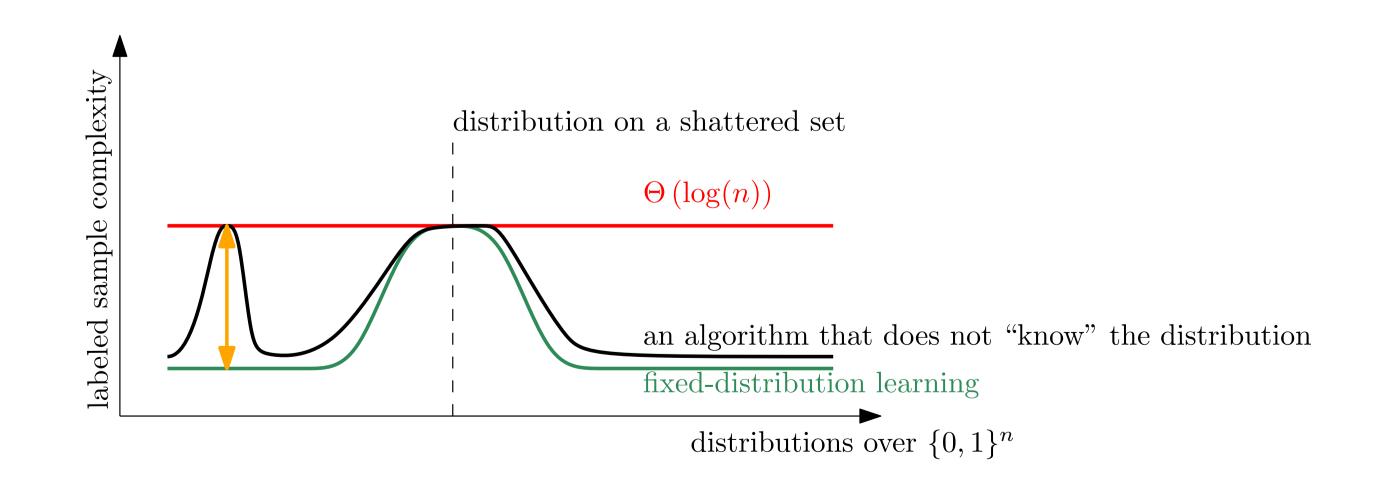
Domain is  $X = \{0,1\}^n$  and hypothesis class is  $H = \{h_1, h_2, \dots, h_n\}$  where

$$h_i(x) = h(x[1], x[2], \dots, x[n]) = x[i]$$

Vapnik-Chervonenkis dimension is  $VC(H) = |\log_2(n)|$ .

**Theorem.** Fix  $\epsilon$  and  $\delta$ . There are distributions  $D_1, D_2, \ldots, D_n$  such that

- 1. With knowledge of the distribution  $D_i$ , sample complexity is O(1).
- 2. Without knowledge of  $D_i$ , sample complexity is  $\Omega(\log n)$ .



Each  $D_i$  is a product distribution such that

$$\Pr_{x \sim D_i}[x[j] = 1] = \begin{cases} 1/2 & \text{if } i = j, \\ \epsilon/4 & \text{if } i \neq j. \end{cases}$$

# **Sketch of Proof**

- $D_i$  has  $\epsilon/2$ -cover of size 2. Thus  $O\left(\frac{\log N_{D,\epsilon/2} + \log(1/\delta)}{\epsilon}\right) = O(1)$  samples are enough to  $\epsilon$ -learn if  $D_i$  is known to the learner.
- Choose  $i \in \{1, 2, \dots, n\}$  at random.
- Choose distribution  $D_i$  and the target to be the projection  $h_i$ .
- Algorithm that does **not** know  $D_i$  and  $h_i$ , sees only the matrix

$$\begin{pmatrix} x_1[1] & x_1[2] & \cdots & x_1[n] & y_1 \\ x_2[1] & x_2[2] & \cdots & x_2[n] & y_2 \\ \vdots & \vdots & \ddots & \vdots \\ x_m[1] & x_m[2] & \cdots & x_m[n] & y_m \end{pmatrix}$$

- Column x[i] matches column y.
- If  $m \leq \log(n)$  then with constant probability at least one other column x[j] matches column y.
- Learner has to pick a column i or j.

For non-proper learners, the proof is more complicated.

### Conclusions

- Unlabeled data help for projections.
- For the class of **all functions**, unlabeled data do **not** help.
- The problem is open for halfspaces and axis-aligned rectangles in  $\mathbb{R}^n$ , and conjuctions and disjuctions in  $\{0,1\}^n$ . They have  $\mathrm{VC}(H) = \Theta(n)$ . The gap could be potentially as big as  $\Omega(n)$ .

### References

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- [4] Steve Hanneke. The optimal sample complexity of PAC learning. *J. Mach. Learn. Res.*, 17(38):1–15, 2016.